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On the Divergence Expression and the Boundary Value of
Modified Magnetic Vector Potential

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Abstract : In this paper , the divergence expression of modified magnetic vector potential \vec{A}^* in a homogeneous medium is obtained using the time harmonic Maxwell 's equations . A boundary value problem of \vec{A}^* is established , and the uniqueness of the solution of the problem is proved . Finally , the validity of the boundary value problem is verified by a time - harmonic field with an analytical solution .

Key words modified magnetic vector potential ; gauge ; boundary value problem ; time harmonic electromagnetic field
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Introduction

In recent years , several numerical methods have been proposed for calculating the eddy current fields , and these methods usually focus on the electromagnetic potentials which can be used to establish the boundary value problems^[1-2]. The widely - used electromagnetic potentials are magnetic vector potential \vec{A} , electric scalar potential φ , modified magnetic vector potential \vec{A}^* , electric vector potential \vec{T} , and magnetic scalar potential Ω . Among these electromagnetic potentials , the definition of modified magnetic vector potential \vec{A}^* ^[3] is of great interest , because \vec{A}^* includes both magnetic vector potential \vec{A} and electric scalar potential φ , reducing the number of variables that need to be solved . In addition , some boundary value problems become easy to be solved when using the modified magnetic vector \vec{A}^* . However , it is noticed that the Coulomb gauge $\nabla \cdot \vec{A}^* = 0$ is not always satisfied for the time harmonic electromagnetic fields . Particularly , $\nabla \cdot \vec{A}^*$ will not be zero when the source currents exist . This fact motivates us to reconsider the governing equations of \vec{A}^* , boundary conditions of \vec{A}^* , and the u-

niqueness of the solution of \vec{A}^* .
The remainder of this paper is as follows . In Sec.1 we give the divergence expression of modified magnetic vector potential \vec{A}^* . In Sec.2 we establish the boundary value problem of \vec{A}^* . In Sec.3 the uniqueness of the solution of \vec{A}^* is proved . In Sec.4 we give an analytical solution of \vec{A}^* for the Sommerfed 's half - space problem . Conclusions are stated in Sec.5 .

1 Divergence Expression of \vec{A}^*

Consider a time harmonic electromagnetic field in a medium with conducting σ , permittivity ϵ , and permeability μ being all constants . We also assume that \vec{J}_s is the time harmonic source current in a limited region in the medium . In this case , the Maxwell 's equations with time factor $e^{j\omega t}$ can be written in the time harmonic forms :

$$\nabla \times \vec{H} = \vec{J}_s + \sigma \vec{E} + j\omega \vec{D} , \tag{1}$$

$$\nabla \times \vec{E} = - j\omega \vec{B} , \tag{2}$$

$$\nabla \cdot \vec{B} = 0 , \tag{3}$$

$$\nabla \cdot \vec{D} = \rho_e . \tag{4}$$

Where \vec{H} is the magnetic field intensity vector , \vec{E} is

the electric field intensity vector, \vec{B} is the magnetic induction vector, \vec{D} is the displacement flux vector, ρ_e is the charge density, ω represents the angular frequency of the time harmonic electromagnetic field, ∇ denotes the Hamilton operator and $j = \sqrt{-1}$.

Using Eq.(3) results in the definition of magnetic vector potential \vec{A} :

$$\vec{B} = \nabla \times \vec{A}. \quad (5)$$

Substituting (5) into (2), we obtain

$$\nabla \times (\vec{E} + j\omega\vec{A}) = 0 \quad (6)$$

and we can introduce an electric scalar potential φ satisfying

$$\vec{E} + j\omega\vec{A} = -\nabla\varphi. \quad (7)$$

Let
$$\vec{A}^* = \vec{A} + \frac{1}{j\omega} \nabla\varphi, \quad (8)$$

then the electric and magnetic field intensity vectors can be written as

$$\vec{E} = -j\omega\vec{A}^* \quad (9)$$

and
$$\vec{H} = \frac{1}{\mu} \nabla \times \vec{A}^*, \quad (10)$$

where \vec{A}^* is known as modified magnetic vector potential. In addition, using Eq.(1) we obtain

$$\nabla \cdot (\nabla \times \vec{H}) = \mu \nabla \cdot \vec{J}_s - j\omega\mu(\sigma + j\omega\epsilon) \nabla \cdot \vec{A}^* \quad (11)$$

and
$$\nabla \cdot \vec{A}^* = -\frac{\mu}{k^2} \nabla \cdot \vec{J}_s, \quad (12)$$

because $\nabla \cdot (\nabla \times \vec{H}) = 0$. In Eq.(12), the factor $k^2 = -j\omega\mu(\sigma + j\omega\epsilon)$. It may be mentioned that the current density \vec{J}_s governs whether the value of $\nabla \cdot \vec{A}^*$ will be zero or not, and it is clearly unnecessary to specify any gauge of \vec{A}^* .

The continuity of currents leads to

$$\nabla \cdot \vec{H}_s = -\nabla \cdot (\vec{J}_e + \vec{J}_d). \quad (13)$$

where \vec{J}_e is the eddy current density and \vec{J}_d is the displacement current density. It can be seen from Eq.(13) that, in general, $\nabla \cdot \vec{J}_s \neq 0$, and thus $\nabla \cdot \vec{A}^* \neq 0$. In this case, the normal component A_n^* of \vec{A}^* is discontinuous across the interface between any two regions that are filled with different mediums, say $A_{1n}^* \neq A_{2n}^*$, and \vec{W} satisfies $\vec{A}^* = \nabla \times \vec{W}$.

2 Boundary Value Problem of \vec{A}^*

Consider a three-dimensional medium-filled region V_1 with medium parameters of σ_1, ϵ_1 , and μ_1 . The medium-filled region V_1 is assumed to be bounded with medium parameters of σ_2, ϵ_2 , and μ_2 , and the source current \vec{J}_s is distributed in a limited region, as shown in Fig.1. In Fig.1, S_1 represents the surface of V_1 with \vec{n}_1 being the outward normal unit vector of S_1 . In addition, the bounded field region $\Omega = V_1 + V_2$ includes the whole field region of interest. It is worth nothing that S_2 is the surface of Ω with \vec{n}_2 being the outward normal unit vector of S_2 . Therefore, the field boundary value problem can be written in the following form for the field region shown in Fig.1:

$$\nabla \times \vec{H} = \vec{J}_s + (\sigma + j\omega\epsilon)\vec{E} \quad \text{in } \Omega; \quad (14)$$

$$\nabla \times \vec{H} = -j\omega\mu\vec{H} \quad \text{in } \Omega; \quad (15)$$

$$(\vec{E}_1 - \vec{E}_2) \times \vec{n}_1 = 0 \quad \text{on } S_1; \quad (16)$$

$$(\vec{E}_1 - \vec{E}_2) \times \vec{n}_1 = \vec{K} \quad \text{on } S_1; \quad (17)$$

$$\vec{E}_2 \times \vec{n}_2 = \vec{\alpha} \quad \text{on } S_2; \quad (18)$$

$$\vec{H}_2 \times \vec{n}_2 = \vec{\beta} \quad \text{on } S_2; \quad (19)$$

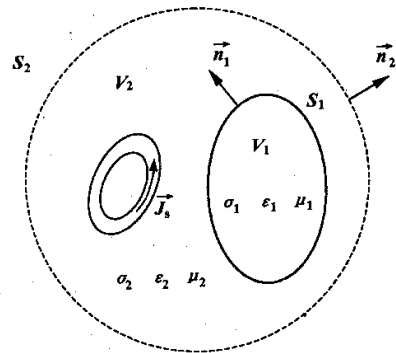


Fig.1 Typical three-dimensional time harmonic electromagnetic fields

where \vec{K} is the surface conducting current density on S_1 and $\vec{\alpha}$ and $\vec{\beta}$ are given vector functions.

On the basis of Helmholtz theorem^[4], to determine a unique vector field, both divergence and curl of the vector field should be specified simultaneously in the field region, and the boundary conditions should also be given. The curl $\nabla \times \vec{A}^*$ satisfies an equation that can be obtained from Eq.(14), while the divergence $\nabla \cdot \vec{A}^*$ satisfies an equation that is given by (12).

Therefore, using the boundary conditions (16), (17), (18), and (19) the boundary value problem of \vec{A}^* in Fig.1 can be written as follow:

$$\nabla \times \nabla \times \vec{A}^* - k^2 \vec{A}^* = \mu \vec{J}_s \quad \text{in } \Omega; \quad (20)$$

$$\nabla \cdot \vec{A}^* = -\frac{\mu}{k^2} \nabla \cdot \vec{J}_s \quad \text{in } \Omega; \quad (21)$$

$$(\vec{A}_1^* - \vec{A}_2^*) \times \vec{n}_1 = 0 \quad \text{on } S_1; \quad (22)$$

$$\left(\frac{1}{\mu_1} \nabla \times \vec{A}_1^* - \frac{1}{\mu_2} \nabla \times \vec{A}_2^* \right) \times \vec{n}_1 = \vec{K} \quad \text{on } S_1; \quad (23)$$

$$\vec{A}_2^* \times \vec{n}_2 = \vec{\alpha} \quad \text{on } S_2; \quad (24)$$

$$\frac{1}{\mu_2} (\nabla \times \vec{A}_2^*) \times \vec{n}_2 = \vec{\beta} \quad \text{on } S_2. \quad (25)$$

3 Uniqueness of the Solution of \vec{A}^*

Two solutions for the boundary value problem (20)~(25) are assumed to be \vec{A}_a^* and \vec{A}_b^* , and the vector \vec{F} is assumed to be $\vec{F} = \vec{A}_a^* - \vec{A}_b^*$. Then the vector \vec{F} satisfies the following boundary value problem:

$$\nabla \times \nabla \times \vec{F} - k^2 \vec{F} = 0 \quad \text{in } \Omega; \quad (26)$$

$$\nabla \cdot \vec{F} = 0 \quad \text{in } \Omega; \quad (27)$$

$$(\vec{F}_1 - \vec{F}_2) \times \vec{n}_1 = 0 \quad \text{on } S_1; \quad (28)$$

$$\left(\frac{1}{\mu_1} \nabla \times \vec{F}_1 - \frac{1}{\mu_2} \nabla \times \vec{F}_2 \right) \times \vec{n}_1 = 0 \quad \text{on } S_1; \quad (29)$$

$$\vec{F}_2 \times \vec{n}_2 = 0 \quad \text{on } S_2; \quad (30)$$

$$\left(\frac{1}{\mu_2} \nabla \times \vec{F}_2 \right) \times \vec{n}_2 = 0 \quad \text{on } S_2; \quad (31)$$

where $\vec{F}_1 = \vec{A}_{a1}^* - \vec{A}_{b1}^*$ and $\vec{F}_2 = \vec{A}_{a2}^* - \vec{A}_{b2}^*$. In addition, letting \vec{F}^c be the complex conjugate of \vec{F} , one can start with the following expression to analyze the problem:

$$\begin{aligned} & \int_{\Omega} \left[\vec{F}^c \cdot \left(\nabla \times \frac{1}{\mu} \nabla \times \vec{F} \right) - \frac{1}{\mu} \nabla \times \vec{F} \cdot \nabla \times \vec{F}^c \right] d\Omega = \int_{V_1} \left[\vec{F}_1^c \cdot \left(\nabla \times \frac{1}{\mu_1} \nabla \times \vec{F}_1 \right) - \frac{1}{\mu_1} \nabla \times \vec{F}_1 \cdot \nabla \times \vec{F}_1^c \right] dV_1 + \int_{V_2} \left[\vec{F}_2^c \cdot \left(\nabla \times \frac{1}{\mu_2} \nabla \times \vec{F}_2 \right) - \frac{1}{\mu_2} \nabla \times \vec{F}_2 \cdot \nabla \times \vec{F}_2^c \right] dV_2. \end{aligned} \quad (32)$$

Using $\vec{P} = \frac{1}{\mu} \nabla \times \vec{F}$, $\vec{Q} = \vec{F}^c$, the integral formula

$$\int_V [\vec{P} \cdot (\nabla \times \vec{Q}) - \vec{Q} \cdot (\nabla \times \vec{P})] dV =$$

$$\oint_S \vec{P} \cdot (\vec{Q} \times \vec{n}) dS, \quad (33)$$

and the boundary condition (28), one can rewrite the right-hand side of Eq.(32):

$$\begin{aligned} & \oint_{S_1} \left(\frac{1}{\mu_1} \nabla \times \vec{F}_1 \right) \cdot (\vec{F}_1^c \times \vec{n}_1) dS_1 - \oint_{S_1} \left(\frac{1}{\mu_2} \nabla \times \vec{F}_2 \right) \cdot (\vec{F}_2^c \times \vec{n}_1) dS_1 + \oint_{S_2} \left(\frac{1}{\mu_2} \nabla \times \vec{F}_2 \right) \cdot (\vec{F}_2^c \times \vec{n}_2) dS_2 = \\ & - \oint_{S_1} \left[\left(\frac{1}{\mu_1} \nabla \times \vec{F}_1 - \frac{1}{\mu_2} \nabla \times \vec{F}_2 \right) \times \vec{n}_1 \right] \cdot \vec{F}_1^c dS_1 + \frac{4\pi}{\mu_2} \lim_{r \rightarrow \infty} (r \nabla \times \vec{F}_2^c \cdot \vec{r} \vec{F}_2^c \times \vec{n}_2), \end{aligned} \quad (34)$$

Substituting boundary conditions (29), (31), and (32) into Eq.(34), one can find that the right-hand side of Eq.(32) equals zero.

On account of Eq.(26), the left-hand side of Eq.(32) can be written as

$$\begin{aligned} & \int_{\Omega} \left[\vec{F}^c \cdot \left(\nabla \times \frac{1}{\mu} \nabla \times \vec{F} \right) - \frac{1}{\mu} \nabla \times \vec{F} \cdot \nabla \times \vec{F}^c \right] d\Omega = \int_{\Omega} \frac{1}{\mu} (k^2 \vec{F}^c \cdot \vec{F} - \nabla \times \vec{F} \cdot \nabla \times \vec{F}^c) d\Omega = \\ & \int_{\Omega} (\omega^2 \epsilon |\vec{F}|^2 - \frac{1}{\mu} |\nabla \times \vec{F}|^2 - j\omega\sigma |\vec{F}|^2) d\Omega. \end{aligned} \quad (35)$$

Because the right-hand side of Eq.(32) equals zero, the real and imaginary parts of Eq.(35) are

$$\int_{\Omega} (\omega^2 \epsilon |\vec{F}|^2 - \frac{1}{\mu} |\nabla \times \vec{F}|^2) d\Omega = 0 \quad (36)$$

$$\text{and} \quad \int_{\Omega} \omega\sigma |\vec{F}|^2 d\Omega = 0. \quad (37)$$

respectively, here $\mu > 0$, $\omega > 0$, $|\vec{F}| \geq 0$ and $|\nabla \times \vec{F}| \geq 0$.

We can see from (37) that $|\vec{F}| = 0$ when $\sigma > 0$, and using $\vec{F} = 0$ in (36) result in $|\nabla \times \vec{F}| = 0$, therefore $\vec{F} = 0$ for $\sigma > 0$. Particularly, for $\sigma = 0$, we can treat this case as a limit that $\sigma > 0$ and σ approaches zero, thus $|\vec{F}| = 0$. These statements imply that the boundary value problem (20)~(25) has a unique solution.

4 Verifying Example

To verify the divergence expression (12) and the boundary value problem (20)~(25), we solve the Sommerfeld's half-space problem to give analytical

solution of \vec{A}^* , as shown in Fig.2.

In Fig.2, (ρ, θ, z) are cylindrical coordinates, and $\vec{e}_\rho, \vec{e}_\theta$ and \vec{e}_z are the usual unit vectors of the cylindrical coordinate system. The region 1 implies $z > 0$ with medium parameters $\sigma_1, \epsilon_1, \mu_0$; the region 2 implies $z < 0$ with medium parameters $\sigma_2, \epsilon_2, \mu_0$. At $\vec{r}_0 = z_0 \vec{e}_z$ of region 2, one can find a vertical time harmonic current element $I l$, whose current density can be expressed in terms of δ function:

$$\vec{J}_s(\vec{r}) = I l \delta(|\vec{r} - \vec{r}_0|) \vec{e}_z, \quad (38)$$

Where \vec{r} is a vector from original point O to the point of interest.

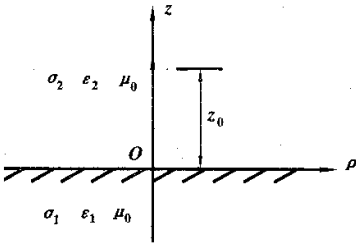


Fig.2 The vertical current element in a homogeneous half-space conducting medium

The equations of field region shown in Fig.2 can be written in the following forms:

$$\nabla \times \nabla \times \vec{A}_1^* - k_1^2 \vec{A}_1^* = 0 \quad (z < 0); \quad (39)$$

$$\nabla \cdot \vec{A}_1^* = 0 \quad (z < 0); \quad (40)$$

$$\nabla \times \nabla \times \vec{A}_2^* - k_2^2 \vec{A}_2^* = \mu_0 I l \delta(|\vec{r} - \vec{r}_0|) \vec{e}_z \quad (z > 0); \quad (41)$$

$$\nabla \cdot \vec{A}_2^* = -\frac{\mu_0 I l}{k_2^2} \frac{\partial}{\partial z} \delta(|\vec{r} - \vec{r}_0|) \quad (z > 0); \quad (42)$$

The boundary conditions are

$$\vec{A}_1^* = \vec{A}_2^* \quad (z = 0), \quad (43)$$

$$\frac{\partial}{\partial z} \vec{A}_1^* - \frac{\partial}{\partial \rho} \vec{A}_{1z}^* = \frac{\partial}{\partial z} \vec{A}_2^* - \frac{\partial}{\partial \rho} \vec{A}_{2z}^* \quad (z = 0). \quad (44)$$

It is noticed that the values of fields at the infinite points are finite. We can obtain the following analytical solution of this problem using a derivation (given in the Appendix):

$$\vec{A}_1^* = h_1 \int_0^\infty \lambda u_1 f \left[-\vec{e}_\rho J_1(\lambda \rho) + \vec{e}_z \frac{\lambda}{u_1} J_0(\lambda \rho) \right] e^{u_1 z} d\lambda, \quad (45)$$

$$\vec{A}_2^* = \frac{I l}{4\pi} \left[\frac{\partial}{\partial z} + \vec{e}_z \left(k_2^2 + \frac{\partial^2}{\partial z^2} \right) \right] \frac{e^{-jk_2 R}}{R} +$$

$$h_2 \int_0^\infty \lambda^2 g \left[\vec{e}_\rho J_1(\lambda \rho) + \vec{e}_z \frac{\lambda}{u_2} J_0(\lambda \rho) \right] e^{-u_2 z} d\lambda, \quad (46)$$

where

$$h_i = \frac{\mu_0 I l}{4\pi k_i^2} \quad (i = 1, 2); \quad (47)$$

$$k_i^2 = -j\omega\mu_0(\sigma_i + j\omega\epsilon_i) \quad (i = 1, 2); \quad (48)$$

$$u_i = (\lambda^2 - k_i^2)^{1/2} \quad (i = 1, 2); \quad (49)$$

$$R = [\rho^2 + (z - z_0)^2]^{1/2}; \quad (50)$$

$$N = k_1^2 u_2 + k_2^2 u_1; \quad (51)$$

$$f = \frac{2\lambda k_1^2}{N} e^{-u_2 z_0}; \quad (52)$$

$$g = \frac{k_1^2 u_2 - k_2^2 u_1}{N} e^{-u_2 z_0}. \quad (53)$$

Also, J_0 and J_1 are the Bessel functions of order 0 and order 1 respectively.

The radiation problem of vertical time harmonic current element shown in Fig.2 has been deeply investigated in history. Reference [5] states the Hertz vector $\vec{\Pi}$ which could be used to solve the boundary value problems. Using the method provided by Ref. [5], one can obtain the solution of $\vec{\Pi}$ in Fig.2:

$$\vec{\Pi}_1 = 2w_1 k_1^2 \int_0^\infty \frac{\lambda}{N} J_0(\lambda \rho) e^{u_1 z - u_2 z_0} d\lambda \vec{e}_z \quad (z < 0); \quad (54)$$

$$\vec{\Pi}_2 = w_2 \left[\frac{e^{-jk_2 R}}{R} + \frac{e^{-jk_2 R_s}}{R_s} - 2k_2^2 \int_0^\infty \frac{\lambda}{N} \cdot \frac{u_1}{u_2} J_0(\lambda \rho) e^{-u_2(z+z_0)} d\lambda \right] \vec{e}_z \quad (z > 0), \quad (55)$$

Where

$$w_i = j\omega h_i \quad (i = 1, 2), \quad (56)$$

$$R_s = [\rho^2 + (z + z_0)^2]^{1/2}. \quad (57)$$

It is easy to verify that substituting (54) and (55) into

$$\vec{A}^* = -\frac{1}{j\omega} (k^2 + \nabla \cdot \nabla) \vec{\Pi}, \quad (58)$$

respectively, one can obtain the same expressions of (45) and (46), which imply that (12) and boundary value problem (20)~(25) are valid and reliable.

5 Conclusions

The divergence expression of modified magnetic vector potential \vec{A}^* is determined by the basic law of time harmonic electromagnetic fields, therefore, it is not necessary to specify any gauge of \vec{A}^* . Generally

speaking, $\nabla \cdot \vec{A}^* \neq 0$.

This paper gives the boundary value problem of modified magnetic vector potential \vec{A}^* , which can be used to solve the three-dimensional time harmonic electromagnetic fields in any arbitrarily complex regions including subregions filled with linear homogeneous mediums.

Appendix: Analytical Solution to the Sommerfeld's Half-space Problem

In the field region of Fig.2, \vec{A}^* can be expressed as

$$\vec{A}^* = \vec{A}_\rho^* \vec{e}_\rho + \vec{A}_z^* \vec{e}_z \text{ and } \frac{\partial}{\partial \theta} \vec{A}^* = 0.$$

A. The General Solutions of Equations (39) and (41)

Because

$$\nabla \times \nabla \times \vec{A}^* = \nabla(\nabla \cdot \vec{A}^*) - \nabla^2 \vec{A}^*, \quad (\text{A1})$$

the Eq.(39) and (41) can be written as

$$(\nabla^2 + k_1^2) \vec{A}_1^* = 0 \quad (\text{A2})$$

and

$$(\nabla^2 + k_2^2) \vec{A}_2^* = -\mu_0 I l \left(\vec{e}_z + \frac{1}{k_2^2} \nabla \frac{\partial}{\partial z} \right) \delta(|\vec{r} - \vec{r}_0|), \quad (\text{A3})$$

respectively. We assume that the vector \vec{S} indicates the right-hand side of Eq.(A3). Using the three-dimensional free-space Green's function-satisfied identical equation

$$\delta(|\vec{r} - \vec{r}'|) = \frac{1}{4\pi} (\nabla^2 + k^2) \frac{e^{-jk|\vec{r} - \vec{r}'|}}{|\vec{r} - \vec{r}'|} \quad (\text{A4})$$

and

$$\frac{\partial}{\partial \rho} \nabla^2 = \left(\nabla^2 - \frac{1}{\rho^2} \right) \frac{\partial}{\partial \rho}, \quad (\text{A5})$$

one can obtain

$$\vec{S} = h_2 \left[\vec{e}_\rho \left(\nabla^2 - \frac{1}{\rho^2} + k_2^2 \right) \frac{\partial^2}{\partial \rho \partial z} + \vec{e}_z \left(\nabla^2 + k_2^2 \right) \left(k_2^2 + \frac{\partial^2}{\partial z^2} \right) \right] \frac{e^{-jk_2 R}}{R}. \quad (\text{A6})$$

Therefore, the equation of components $A_{1\rho}^*$, A_{1z}^* , $A_{2\rho}^*$, and A_{2z}^* can be written as

$$\left(\nabla^2 - \frac{1}{\rho^2} + k_1^2 \right) A_{1\rho}^* = 0, \quad (\text{A7})$$

$$(\nabla^2 + k_1^2) A_{1z}^* = 0, \quad (\text{A8})$$

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$$\left(\nabla^2 - \frac{1}{\rho^2} + k_2^2 \right) \left(A_{2\rho}^* - h_2 \frac{\partial^2}{\partial \rho \partial z} \frac{e^{-jk_2 R}}{R} \right) = 0 \quad (\text{A9})$$

and

$$(\nabla^2 + k_2^2) \left[A_{2z}^* - h_2 \left(k_2^2 + \frac{\partial^2}{\partial z^2} \right) \frac{e^{-jk_2 R}}{R} \right] = 0. \quad (\text{A10})$$

The general solutions of (A7), (A8), (A9), and (A10) can be obtained by using the separation of variables[1]:

$$A_{1\rho}^* = \int_0^\infty J_1(\lambda \rho) \{ a_1 e^{-u_1 z} + a_2 e^{u_1 z} \} d\lambda \quad (z < 0), \quad (\text{A11})$$

$$A_{1z}^* = \int_0^\infty J_0(\lambda \rho) \{ b_1 e^{-u_1 z} + b_2 e^{u_1 z} \} d\lambda \quad (z < 0), \quad (\text{A12})$$

$$A_{2\rho}^* = h_2 \frac{\partial^2}{\partial \rho \partial z} \frac{e^{-jk_2 R}}{R} + \int_0^\infty J_1(\lambda \rho) \{ c_1 e^{-u_2 z} + c_2 e^{u_2 z} \} d\lambda \quad (z > 0), \quad (\text{A13})$$

$$A_{2z}^* = h_2 \left(k_2^2 + \frac{\partial^2}{\partial z^2} \right) \frac{e^{-jk_2 R}}{R} + \int_0^\infty J_0(\lambda \rho) \{ d_1 e^{-u_2 z} + d_2 e^{u_2 z} \} d\lambda \quad (z > 0), \quad (\text{A14})$$

where a_i, b_i, c_i and d_i are the undetermined constants with $i = 1, 2, 3, 4$; J_n is the Bessel function of order n of the first kind,

B. The Determination of Constants a_i, b_i, c_i and d_i

We assume that the real parts of u_i and k_i are positive. Because the values of fields are finite at the infinite points, we can obtain

$$a_1 = 0, \quad b_1 = 0;$$

$$c_2 = 0, \quad d_2 = 0,$$

and only four constants a_2, b_2, c_1 and d_1 need to be determined.

Substituting (A11) and (A12) into (40) results in

$$\lambda a_2 + u_1 b_2 = 0 \quad (\text{A15})$$

Letting M be the right-hand side of (42), and using (A4), one can get

$$M = h_2 \frac{\partial}{\partial z} \left(\nabla^2 + k_2^2 \right) \frac{e^{-jk_2 R}}{R}. \quad (\text{A16})$$

In addition, substituting (A13), (A14) and (A16) into (42), one can write

$$\lambda c_1 - u_2 d_1 = 0. \quad (\text{A17})$$

Employing the Sommerfeld's integral formula[5]

$$\frac{e^{-jk\sqrt{\rho^2+z^2}}}{\sqrt{\rho^2+z^2}} = \int_0^\infty \frac{\lambda}{\sqrt{\lambda^2-k^2}} J_0(\lambda\rho) e^{-\sqrt{\lambda^2-k^2}|z|} d\lambda, \tag{A18}$$

all terms of right – hand side of (A13) can be expressed in the integral forms ,and in this case the boundary condition (43) leads to

$$a_2 - c_1 = - h_2 \lambda^2 e^{-u_2 z_0}. \tag{A19}$$

Similarly ,the right – hand side of (A14) can also be expressed in the integral form by using (A18) and the boundary condition (44) leads to

$$u_1 a_2 + \lambda b_2 + u_2 c_1 - \lambda d_1 = \frac{h_2 k_2^2 \lambda^2}{u_2} e^{-u_2 z_0}. \tag{A20}$$

Therefore ,using (A15) (A17) (A19) and (A20) , one can obtain

$$\begin{aligned} a_2 &= - h_1 \lambda u_1 f, \quad b_2 = h_1 \lambda^2 f, \\ c_1 &= h_2 \lambda^2 g, \quad d_1 = \frac{h_2 \lambda^3}{u_2} g. \end{aligned}$$

Substituting the expressions of a_2, b_2, c_1 and d_1 into (A11) (A12) (A13) and (A14) ,one will get the results of (45) and (46).

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修正矢量磁位的散度及其边值问题

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摘 要 : 根据时谐形式的麦克斯韦方程组 ,导出了均匀媒质中修正矢量磁位 \vec{A}^* 的散度表达式 . 在此基础上 ,建立了 \vec{A}^* 的边值问题 ,并证明 \vec{A}^* 解答的唯一性 ,最后以有解析解的时谐场为例验证了本文建立的边值问题的正确性 .

关键词 : 修正矢量磁位 ; 规范 ; 边值问题 ; 时谐电磁场